

ON j -LIPSCHITZIAN MAPPINGS IN PSEUDOMETRICALLY CONVEX UNIFORM SPACES

Vasil Angelov

University of Mining and Geology
"St. Ivan Rilski"
Sofia 1700
Bulgaria

SUMMARY

Conditions guaranteeing global j -Lipschitzicity of mappings defined in complete pseudometrically convex uniform spaces are given. Such mappings arise in many applications mentioned in the references.

Let (X, \mathbf{A}) be a complete T_2 -separated uniform space whose uniformity is generated by a saturated family of pseudometrics $\mathbf{A} = \{d_a(x, y) : a \in A\}$, where A is an index set. Basic notions concerning the uniform spaces can be found in (Weil, 1938; Kelley, 1959; Isbell, 1964; Page, 1978). A uniform space (X, \mathbf{A}) is said to be pseudometrically convex if for every $x, y \in X$ there is $z \in X (z \neq x \neq y)$ such that

$$d_a(x, y) = d_a(x, z) + d_a(z, y)$$

for every $a \in A$ provided $d_a(x, y) > 0$ (cf. Angelov et al., 1997). The metrical segment between x and y with respect to the pseudometric $d_a(.,.)$ we denote by $[x, y]_a$, $a \in A$ and

$$(x, y)_a = [x, y]_a \setminus \{x, y\}.$$

Let $j : A \rightarrow A$ be a map of the index set into itself whose iterates are defined inductively as follows

$$j^0(a) = a, j^k(a) = j(j^{k-1}(a)) \quad (k \in \mathbb{N}).$$

Further on by (X, \mathbf{A}) and (Y, \mathbf{A}) we mean uniform spaces whose index sets for their families of pseudometrics coincide, i.e. we have

$$(X, \{d_a(x, y) : a \in A\}), (Y, \{d_a(x, y) : a \in A\}).$$

Let $\{M_a\}_{a \in A}$ be a family of positive constants where A is the same index set. A mapping $T : X \rightarrow Y$ is called j -Lipschitzian if for every $x, y \in X$ is satisfied

$$d_a(Tx, Ty) \leq M_a d_{j(a)}(x, y) \quad \text{for } a \in A.$$

The main goal of the present note is to formulate local conditions which imply the j -Lipschitzian character of mappings defined in complete pseudometrically convex uniform spaces. Such mappings are generated by functional differential equations treated in (Angelov, 1987; 1989, 2000).

Prior to formulate the main result we present an example of pseudometrically convex uniform space. Consider the set $C(R^1)$ of all continuous functions $f : R^1 \rightarrow R^1$. Let us fix an arbitrary function $b(\cdot) \in C(R^1)$ and assume that $b(t)$ is unbounded and positive on R^1 . Define the set $C_b(R^1) = \{f \in C(R^1) : |f(t)| \leq b(t)\}$. It is easy to see that the sum of two functions from $C_b(R^1)$ does not belong to $C_b(R^1)$ in general case. This means $C_b(R^1)$ is neither a Banach space nor linear topological space. Denote by A the family of all compact intervals $a = [p, q] \subset R^1$ and introduce a family of pseudometrics $\mathbf{A} = \{d_a(f, g) : a \in A\}$ on $C_b(R^1)$ where

$$d_a(f, g) = \|f - g\|_a, \|f\|_a = \sup\{|f(t)| : t \in a\}.$$

For every $f, g \in C_b(R^1)$ with $f \neq g$ we define the functions $h_\lambda = (1 - \lambda)f + \lambda g$, where the parameter $\lambda \in [0, 1]$. For each fixed $a \in A$ we have

$$d_a(f, h_\lambda) = \|f - (1 - \lambda)f - \lambda g\|_a = \lambda d_a(f, g)$$

$$d_a(g, h_\lambda) = \|g - (1 - \lambda)f - \lambda g\|_a = (1 - \lambda) d_a(f, g).$$

Obviously $d_a(f, g) = d_a(f, h_\lambda) + d_a(h_\lambda, g)$. So by $[f, g]_a$ we denote the closed metrical segment $[f, g]_a = \{h_\lambda : \lambda \in [0, 1]\}$, while by $(f, g)_a = \{h_\lambda : \lambda \in (0, 1)\}$. It is easy to verify that $d_a(f, g) > 0$ implies $d_a(f, h_\lambda) > 0$ and $d_a(g, h_\lambda) > 0$ for $\lambda \in (0, 1)$ and vice versa.

The mapping $T: X \rightarrow Y$ is said to be almost directionally j -Lipschitzian on X if for each $x, y \in X$ with $x \neq y$ the following inequality holds:

$$\inf \left[\frac{d_a(Tx, Tz)}{d_{j(a)}(x, z)} : z \in (x, y)_{j(a)} \right] \leq M_a \quad (1)$$

for $d_{j(a)}(x, y) > 0$ and $d_a(Tx, Ty) = 0$ for $d_{j(a)}(x, y) = 0$.

The above definition extends the corresponding notion in metric spaces (cf. Kirk et al., 1977).

For $d_{j(a)}(x, y) = 0$ there is no metrical segment between x and y with respect to $j(a)$.

Recall that a mapping $T: X \rightarrow Y$ is closed if for $\{x_n\} \subset X$ the conditions $\lim_n x_n = x$ and $\lim_n T(x_n) = y$ imply $x \in X$ and $Tx = y$.

THEOREM. Let (X, \mathbf{A}) and (Y, \mathbf{A}) be complete T_2 -separated uniform spaces with (X, \mathbf{A}) being pseudometrically convex. Let $T: (X, \mathbf{A}) \rightarrow (Y, \mathbf{A})$ be almost directionally j -Lipschitzian mapping with a family of positive constants $\{M_a\}_{a \in A}$. If T is closed, then T is j -Lipschitzian mapping on the whole (X, \mathbf{A}) .

Proof: Let x and y be two distinct elements of X , i.e. $x \neq y$. Let us choose a new family of positive constants $\{M'_a\}_{a \in A}$ such that $M'_a > M_a$ for every fixed $a \in A$. By Ω we denote the countable ordinals and fixed $\gamma \in \Omega$ (cf. Ch.XV, Angelov, 1987). For all $\alpha \in \Omega$ less than γ define the set $\{x_\alpha\}$ so that

($\gamma 1$) $x_0 = x$;

($\gamma 2$) if $x_\alpha = y$ for some α and $\alpha \leq \eta < \gamma$, then $x_\eta = y$;

($\gamma 3$) if $\alpha < \beta < \eta < \gamma$ and $x_\eta \neq y$, then $x_\beta \in (x_\alpha, x_\eta)_{j(a)}$

for those $a \in A$ for which $d_{j(a)}(x_\alpha, x_\eta) > 0$;

($\gamma 4$) If $\beta < \eta < \gamma$ and $x_\eta \neq y$, then $x_\eta \in (x_\beta, y)_{j(a)}$;

($\gamma 5$) T is j -Lipschitzian with a family $\{M'_a\}_{a \in A}$ on the set $\{x_\eta : \eta < \gamma\}$.

If γ has a predecessor $\mu \in \Omega$, that is, $\gamma = \mu + 1$, then we put $x_\gamma = y$.

If $x_\mu \neq y$ and $d_{j(a)}(x_\mu, y) > 0$ in view of the definition (1) we choose $x_\gamma \in (x_\mu, y)_{j(a)}$ so that

$$d_a(Tx_\gamma, Tx_\mu) \leq M'_a d_{j(a)}(x_\gamma, x_\mu)$$

(recall that $d_{j(a)}(x_\mu, y) > 0$ implies $d_{j(a)}(x_\mu, x_\gamma) > 0$).

In what follows we show that ($\gamma 1$)- ($\gamma 3$) hold for $\eta = \gamma$. If $\alpha < \mu$, then ($\gamma 4$) implies

$$\begin{aligned} d_{j(a)}(x_\alpha, x_\gamma) &\leq d_{j(a)}(x_\alpha, x_\mu) + d_{j(a)}(x_\mu, x_\gamma) = \\ &= d_{j(a)}(x_\alpha, y) - d_{j(a)}(x_\mu, y) + d_{j(a)}(x_\mu, y) - d_{j(a)}(x_\gamma, y) = \text{that} \\ &= d_{j(a)}(x_\alpha, y) - d_{j(a)}(x_\gamma, y) \leq d_{j(a)}(x_\alpha, x_\gamma), \\ \text{is, } d_{j(a)}(x_\alpha, x_\gamma) &= d_{j(a)}(x_\alpha, x_\mu) + d_{j(a)}(x_\mu, x_\gamma) \text{ or} \end{aligned}$$

$x_\mu \in (x_\alpha, x_\gamma)_{j(a)}$. If $\alpha < \beta < \mu < \gamma$, then ($\gamma 3$) implies

$$\begin{aligned} d_{j(a)}(x_\alpha, x_\gamma) &= d_{j(a)}(x_\alpha, x_\mu) + d_{j(a)}(x_\mu, x_\gamma) = \\ &= d_{j(a)}(x_\alpha, x_\beta) + d_{j(a)}(x_\beta, x_\mu) + d_{j(a)}(x_\mu, x_\gamma) \geq \\ &\geq d_{j(a)}(x_\alpha, x_\beta) + d_{j(a)}(x_\beta, x_\gamma) \geq d_{j(a)}(x_\alpha, x_\gamma), \end{aligned}$$

that is $d_{j(a)}(x_\alpha, x_\gamma) = d_{j(a)}(x_\alpha, x_\beta) + d_{j(a)}(x_\beta, x_\gamma)$ which means $x_\beta \in (x_\alpha, x_\gamma)_{j(a)}$. So ($\gamma 3$) is thus proved for $\eta = \gamma$.

For $\beta < \gamma$ we have

$$\begin{aligned} d_{j(a)}(x_\beta, y) &= d_{j(a)}(x_\beta, x_\mu) + d_{j(a)}(x_\mu, y) = \\ &= d_{j(a)}(x_\beta, x_\mu) + d_{j(a)}(x_\mu, x_\gamma) + d_{j(a)}(x_\gamma, y). \\ &= d_{j(a)}(x_\beta, x_\gamma) + d_{j(a)}(x_\gamma, y) \end{aligned}$$

Therefore ($\gamma 4$) holds for $\eta = \gamma$.

We have to show that ($\gamma 5$) holds for $\eta = \gamma$.

Suppose $\beta < \gamma$. As we have already shown $x_\beta \in (x_\alpha, x_\gamma)_{j(a)}$ and

$$\begin{aligned} d_a(Tx_\beta, Tx_\gamma) &\leq d_a(Tx_\beta, Tx_\mu) + d_a(Tx_\mu, Tx_\gamma) \leq \\ &\leq M'_a d_{j(a)}(x_\beta, x_\mu) + M'_a d_{j(a)}(x_\mu, x_\gamma) = M'_a d_{j(a)}(x_\beta, x_\gamma) \end{aligned}$$

which proves ($\gamma 5$).

If $\gamma \in \Omega$ is a limit ordinal, then we can choose a increasing sequence of ordinals $\{\gamma_n\}_{n=1}^\infty$, $\gamma_n \in \Omega$ such that $\lim_n \gamma_n = \gamma$. In view of ($\gamma 1$) and ($\gamma 3$)

$$d_{j(a)}(x_0, x_{\gamma_{n+1}}) = d_{j(a)}(x_0, x_{\gamma_n}) + d_{j(a)}(x_{\gamma_n}, x_{\gamma_{n+1}})$$

which implies $d_{j(a)}(x_0, x_{\gamma_{n+1}}) \geq d_{j(a)}(x_0, x_{\gamma_n})$,

that is, the sequence $\{d_{j(a)}(x_0, x_{\gamma_n})\}_{n=1}^{\infty}$ is non-decreasing.

Since $(\gamma 4)$ implies

$$\begin{aligned} d_{j(a)}(x_0, y) &= d_{j(a)}(x_0, x_{\gamma_n}) + d_{j(a)}(x_{\gamma_n}, y), \\ d_{j(a)}(x_0, x_{\gamma_n}) &= d_{j(a)}(x_0, y) - d_{j(a)}(x_{\gamma_n}, y) \\ \text{or } d_{j(a)}(x, x_{\gamma_n}) &\leq d_{j(a)}(x, y) \end{aligned}$$

which implies the convergence of the sequence $\{d_{j(a)}(x_0, x_{\gamma_n})\}_{n=1}^{\infty}$. If we put $x_{\gamma_0} = x$ then

$$d_{j(a)}(x, x_{\gamma_n}) = \sum_{k=0}^{n-1} d_{j(a)}(x_{\gamma_k}, x_{\gamma_{k+1}}),$$

which implies

$$\sum_{k=0}^{\infty} d_{j(a)}(x_{\gamma_k}, x_{\gamma_{k+1}}) \leq d_{j(a)}(x, y) < \infty.$$

This means that $\{x_{\gamma_n}\}_{n=0}^{\infty}$ is a Cauchy sequence in (X, \mathbf{A}) . The completeness of X implies an existence of an element $z \in X$ such that $\lim_n x_{\gamma_n} = z$. We can define $x_{\gamma} = z$.

If for any $\alpha < \gamma$ we have $x_{\alpha} = y$, then $\{x_{\gamma_n}\}$ is eventually the constant sequence $\{y\}$. In this case $(\gamma 2) - (\gamma 5)$ are satisfied for $\eta = \gamma$.

Since $\gamma_n < \gamma$ then $(\gamma 5)$ implies

$$d_a(Tx_{\gamma_n}, Tx_{\gamma_m}) \leq M'_a d_{j(a)}(x_{\gamma_n}, x_{\gamma_m})$$

for all m and n . We can assume without loss of generality that $d_{j(a)}(x_m, x_n) > 0$. Otherwise we remove the elements for which $d_{j(a)}(x_m, x_n) = 0$ and renumber the rest ones. Consequently $\{Tx_{\gamma_n}\}_n$ is a Cauchy sequence in Y . But Y is a complete uniform space and T has a closed graph. Then $\lim_n Tx_{\gamma_n} = Tx_{\gamma}$. Let $\alpha < \beta < \gamma$ and let n be chosen sufficiently large such that $\gamma_n \geq \beta$. In view of $(\gamma 3)$ we have

$$d_{j(a)}(x_{\alpha}, x_{\gamma_n}) = d_{j(a)}(x_{\alpha}, x_{\beta}) + d_{j(a)}(x_{\beta}, x_{\gamma_n}).$$

Passing to the limit $n \rightarrow \infty$ in the last equality we obtain

$$d_{j(a)}(x_{\alpha}, x_{\gamma}) = d_{j(a)}(x_{\alpha}, x_{\beta}) + d_{j(a)}(x_{\beta}, x_{\gamma}),$$

that is, $x_{\beta} \in (x_{\alpha}, x_{\gamma})_{j(a)}$. Also $(\gamma 4)$ implies

$$d_{j(a)}(x_{\beta}, y) = d_{j(a)}(x_{\beta}, x_{\gamma_n}) + d_{j(a)}(x_{\gamma_n}, y)$$

Recommended for publication by Department of Mathematics, Faculty of Mining Electromechanics

and after $n \rightarrow \infty$ we obtain $x_{\gamma} \in (x_{\beta}, y)_{j(a)}$. Consequently $(\gamma 3)$ and $(\gamma 4)$ are satisfied for $\eta = \gamma$. Condition $(\gamma 5)$ implies

$$d_a(Tx_{\beta}, Tx_{\gamma_n}) \leq M'_a d_{j(a)}(x_{\beta}, x_{\gamma_n})$$

(provided $d_{j(a)}(x_{\beta}, x_{\gamma_n}) > 0$) hence by $n \rightarrow \infty$

$$d_a(Tx_{\beta}, Tx_{\gamma}) \leq M'_a d_{j(a)}(x_{\beta}, x_{\gamma}).$$

Finally we obtained a set $\{x_{\gamma} : \gamma \in \Omega\}$ in X so that $(\gamma 1) - (\gamma 5)$ are satisfied. If $x_{\gamma} \neq y$ for all $\gamma \in \Omega$ then $(\gamma 3)$ implies that the set $Z = \{d_{j(a)}(x, x_{\gamma}) : \gamma \in \Omega\}$ is a discrete set of real numbers. In view of Theorem 2, Ch. XV, (Sierpinski, 1965) Z is non-denumerable set. The obtained contradiction implies that for some $\gamma \in \Omega$, $x_{\gamma} = y$ and then $(\gamma 5)$ implies

$$d_a(Tx, Ty) \leq M'_a d_{j(a)}(x, y).$$

The last inequality is valid for arbitrary $M'_a > M_a$ and consequently

$$d_a(Tx, Ty) \leq M_a d_{j(a)}(x, y).$$

Theorem is thus proved.

REFERENCES

- Weil A. 1938. Sur les espaces a structure uniforme et sur la topologie generale. Hermann, Paris.
- Kelley J. L. 1959. General Topology. D. Van Nostrand Company, New York.
- Isbell J. R. 1964. Uniform Spaces. AMS, Providence, RI.
- Page W. 1978. Topological Uniform Structures. J. Wiley & Son, New York.
- Angelov V., L. Georgiev. 1997. An extension of Kirk-Schöneberg theorem to uniform spaces. *Discussiones Mathematicae, Differential Inclusions*, v.17, 89-96.
- Angelov V. 1987. Fixed point theorems in uniform spaces and applications. *Czechoslovak Math. J.*, v.37, 19-33.
- Angelov V. 1989. Fixed points of densifying mappings in locally convex spaces and applications. *J. Institute of Mathematics and Computer Sci. (Calcutta)*, v.2, N2, 22-39.
- Angelov V. 2000. Escape trajectories of J.L. Synge equations. *J. Nonlinear Analysis. Real World Applications*. V.1, 189-204.
- Kirk W. A., W. O. Ray. 1977. A note on Lipschitzian mappings in convex metric spaces. *Canad. Math. Bull.* v.20 (4), 463-466.
- Sierpinski W. 1965. Cardinal and Ordinal Numbers. Warszawa.